



KI•LINE *Vision* in group control

KI•LINE *Vision* uses CAN interface to communicate in the group control bus with other *Vision* systems, and together they form a traffic system.

Every *Vision* system work independently in a group of other systems. The information being sent between all systems are:

- where you are
- where you're going
- alarm, status
- reserved job

Each system knows the *distances* between floors and the nominal *speed* on the lift as well as the average *time* for serving a floor. The systems use this information to calculate which lift is the most suitable for the job, even if the conditions change during the time.